1. Theoretical RPM/Speed vs Actual
2. Chart of Battery power over time AS THE ROBOT CONSTANTLY RUNS → make sure it runs to 2 mins at least
3. Video of battle bot making another bot trip up or flip
4. Weigh the battle bot → under 2 lbs → weighing machine in open lab
5. Collect latency values and average them out → idk ishanvi make some visual
6. Show how kill switch works → both the stop button and removing wifi
7. Send commands to bot and see how far it can run distance wise → do in hallway → find the max and maybe measure the latency as distance increases → make visual